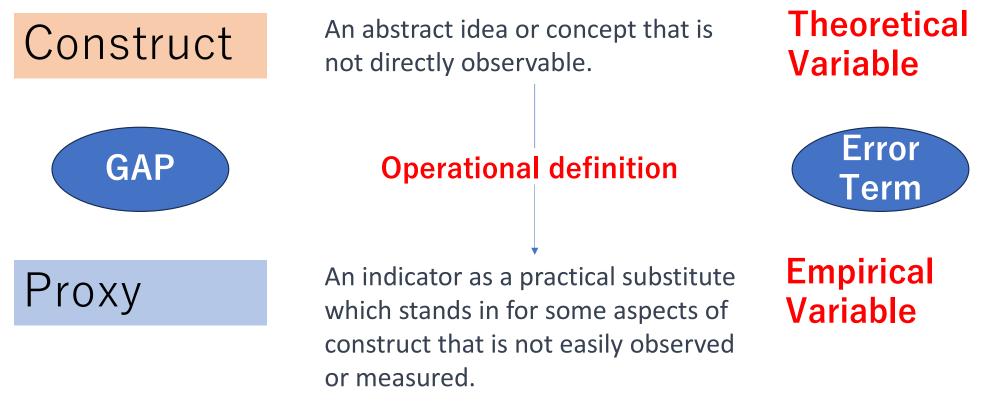
### One proxy variable for multiple unobserved confounders, what kind of bias can arise?

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### Constructs and Proxies in Social science studies



# ☑Validity of measurement☑Validity of inference

When focusing on the validity of the measurement, an accurate proxy is one with fewer error terms.

=evaluate the proxy by its correlation with the construct

When focusing on the validity of the inference, a preferable proxy is one that results in a more unbiased causal inference.

=evaluate the proxy by a framework for sensitivity analysis.

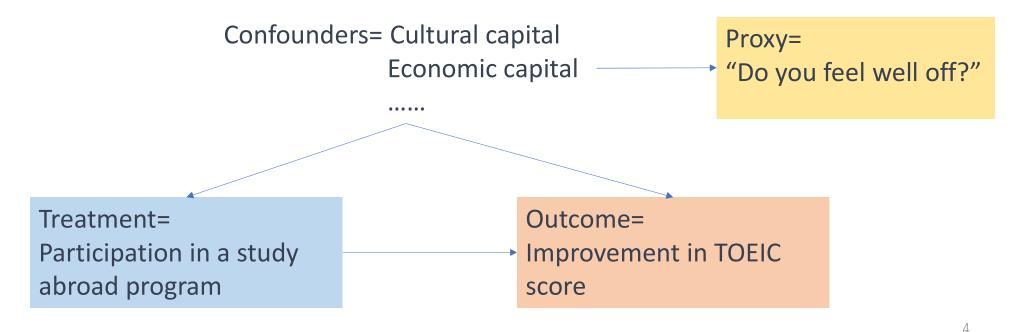
#### A pragmatism approach~

A proxy, although not the most accurate, may still produce unbiased results in causal inference.

On the other hand, in some cases, suppressing the error terms could actually amplify the bias in causal inference.

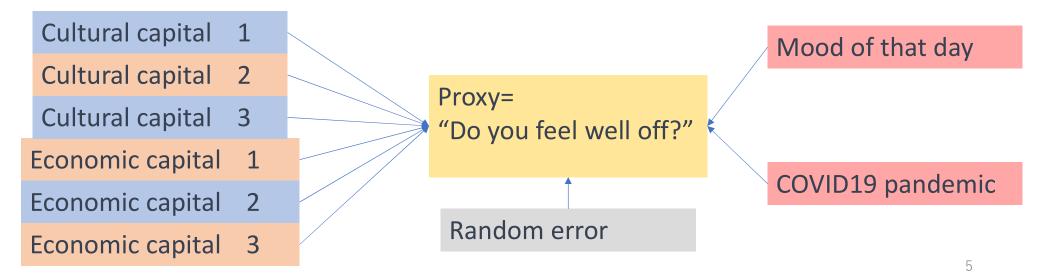
### Proxy for Confounder(s)

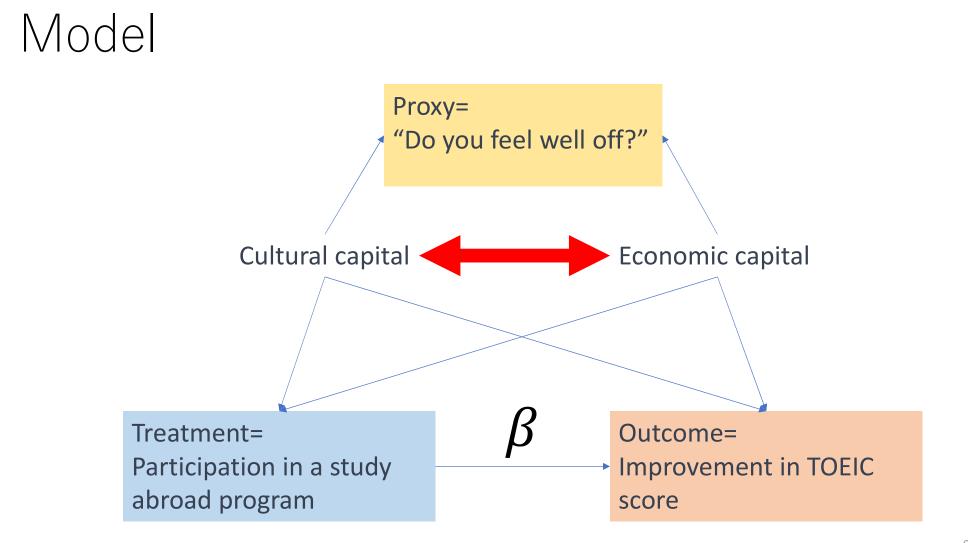
- Causal inference in social science frequently encounters confounding variables that are abstract constructs, which aren't directly measurable.
- By using operational definitions, it is possible to control confounders partially.



# What happens if we control only one proxy for multiple unobserved confounders?

- A construct like "Cultural capital" or "Economic capital" may encompass various meanings.
- Controlling for just one proxy means attempting to encapsulate multiple confounders within a single dimension.

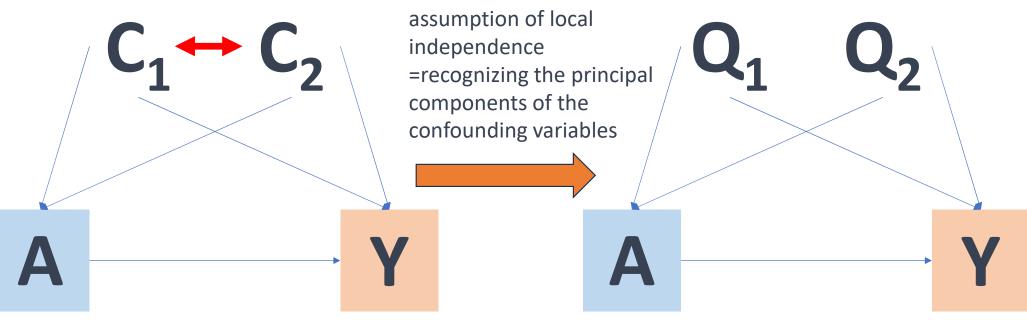




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### Assumption of local independence

To calculate the bias, one of the challenges is that the causality among the confounders can be also considered. This makes calculation quite complex.



### The generation process of proxy

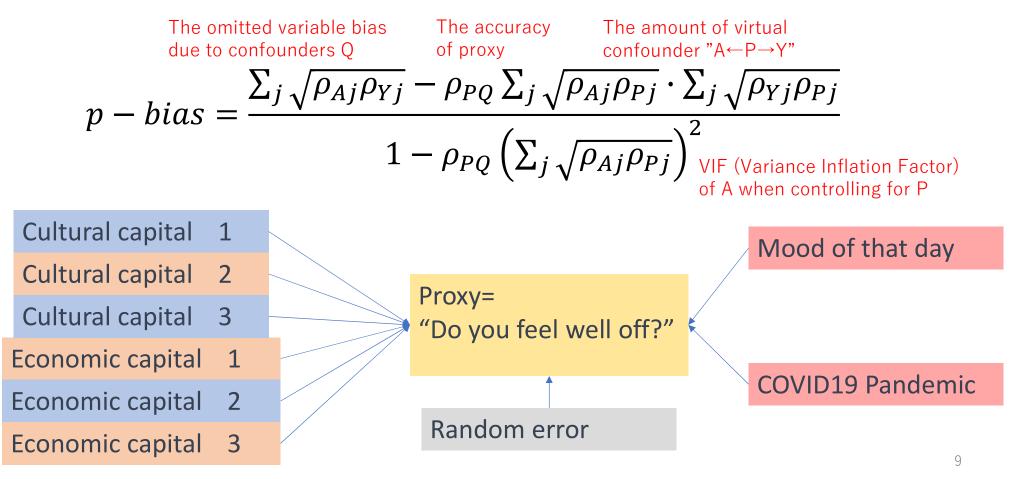
$$P_{i} = \sum_{j} Q_{ij}T_{j} + U_{i}$$
$$P = QT + U$$

The proxy P is determined by the sum of the impacts given by each dimension of the confounders  $Q_i$ , each with its own weight  $T_i$ . U is the term of random errors.

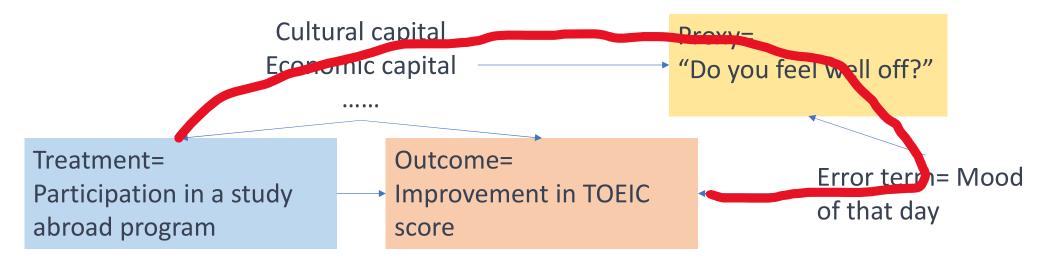
$$\mathbf{Y} = b_0 + b_1 \mathbf{A} + b_2 \mathbf{P}$$

We are going to calculate the deviation of the estimated treatment effect  $(b_1)$  from the true value ( $\beta$ ) when such proxy is controlled for. **The proxy caused bias** = "p-bias" <sub>8</sub>

# P-bias written with part correlation coefficients



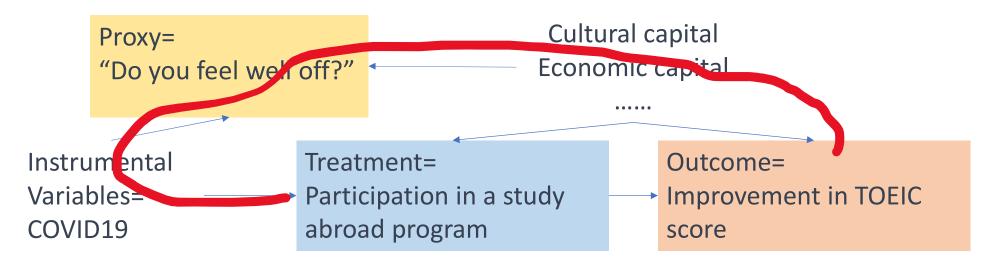
### P influenced by the error term of outcomes



$$p - bias = \frac{\sum_{j} \sqrt{\rho_{Aj} \rho_{Yj}} - \rho_{PQ} \sum_{j} \sqrt{\rho_{Yj} \rho_{Pj}} \sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}} - \rho_{PQ} \sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}} \sum_{r} \sqrt{\rho_{Yr} \rho_{Pr}}}{1 - \rho_{PQ} \left(\sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}}\right)^{2}}$$

\* Back-door path "A $\leftarrow$ Q $\rightarrow$ P $\leftarrow$ Y" has been opened due to controlling for P.

### P influenced by instrumental variables



$$p - bias = \frac{\sum_{j} \sqrt{\rho_{Aj} \rho_{Yj}} - \rho_{PQ} \sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}} \sum_{j} \sqrt{\rho_{Yj} \rho_{Pj}} - \rho_{PQ} \sum_{r} \sqrt{\rho_{Ar} \rho_{Pr}} \sum_{j} \sqrt{\rho_{Yj} \rho_{Pj}}}{1 - \rho_{PQ} \left( \sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}} + \sum_{r} \sqrt{\rho_{Ar} \rho_{Pr}} \right)^{2}}$$

\*Back-door path "A  $\leftarrow$  IV  $\rightarrow$  P  $\leftarrow$  Q  $\leftarrow$  Y" has been opened due to controlling for P.

\*The denominator became smaller. In other words, the VIF (Variance Inflation Factor) increased. This suggests an increase in multicollinearity between A and P, leading to an expansion of estimation bias.

Let's ignore the random error term in the proxy. Is it always safe to control for such proxy?

No random error = an extremely accurate proxy

$$P = QT$$

• What happens if we control for such proxy?

Intuitively, one might think that while it's aggregating multiple confounders into a single proxy, it might not cover all the information, however, it would likely be better than not controlling for anything.

- No! In some case, controlling for the proxy might actually increase the estimation bias, even there is no random error term.
- From the theory of causal inference and the perspective of DAG, this can be explained by the collider bias and the VIF exaggeration due to controlling P.

#### From a geometrical perspective

Vectors concern to the generating processes of A, Y and P  $Dot product of <math>\varrho_A$  and  $\varrho_Y$  $Dot product of <math>\varrho_A$  and  $\varrho_P$  $p - bias = \frac{\sum_j \sqrt{\rho_{Aj} \rho_{Yj}} - \sum_j \sqrt{\rho_{Aj} \rho_{Pj}} \cdot \sum_j \sqrt{\rho_{Yj} \rho_{Pj}}}{1 - \left(\sum_j \sqrt{\rho_{Aj} \rho_{Pj}}\right)^2}$ Dot product of  $\varrho_A$  and  $\varrho_P$ 

- $\rho_{Aj}$  = The portion of variable A determined by  $Q_j$ The **part correlation coefficient** of the j-th confounder  $Q_j$  towards treatment A.
- $\rho_{Yj}$  = The portion of variable Y determined by  $Q_j$ The **part correlation coefficient** of the j-th confounder  $Q_j$  towards outcome Y.
- *ρ*<sub>Pj</sub> = The portion of variable P determined by Q<sub>j</sub>
   The part correlation coefficient of the j-th
   confounder Q<sub>j</sub> towards proxy P.

Let vector  $\rho_A$  be the vector formed by arranging  $\sqrt{\rho_{Aj}}$ Let vector  $\rho_Y$  be the vector formed by arranging  $\sqrt{\rho_{Yj}}$ Let vector  $\rho_P$  be the vector formed by arranging  $\sqrt{\rho_{Pj}}$ 

#### Part correlation coefficient

$$\sum_{j} \rho_{Aj} = \sum_{j} \rho_{Pj} = 1$$
$$\sum_{j} \rho_{Yj} = 1 - \beta^{2}$$

$$\|\varrho_A\| = \|\varrho_P\| = 1$$
  
 $\|\varrho_Y\| = \sqrt{1 - \beta^2}$ 

So that…

$$-bias = \sqrt{1 - \beta^2} \frac{cosAY - cosAP \cdot cosYP}{1 - (cosAP)^2}$$

The emitted variable bies

•  $\sum_{j} \sqrt{\rho_{Aj} \rho_{Yj}}$  is the  $\sqrt{1 - \beta^2}$  times cosine of the angle between  $\varrho_A$ and  $\varrho_Y$  ~cosAY

p

- $\sum_{j} \sqrt{\rho_{Aj} \rho_{Pj}}$  is the cosine of the angle between  $\varrho_A$  and  $\varrho_P$ ~cosAP
- $\sum_{j} \sqrt{\rho_{Yj} \rho_{Pj}}$  is the  $\sqrt{1 \beta^2}$  times cosine of the angle between  $\varrho_Y$ and  $\varrho_P$  ~cosYP

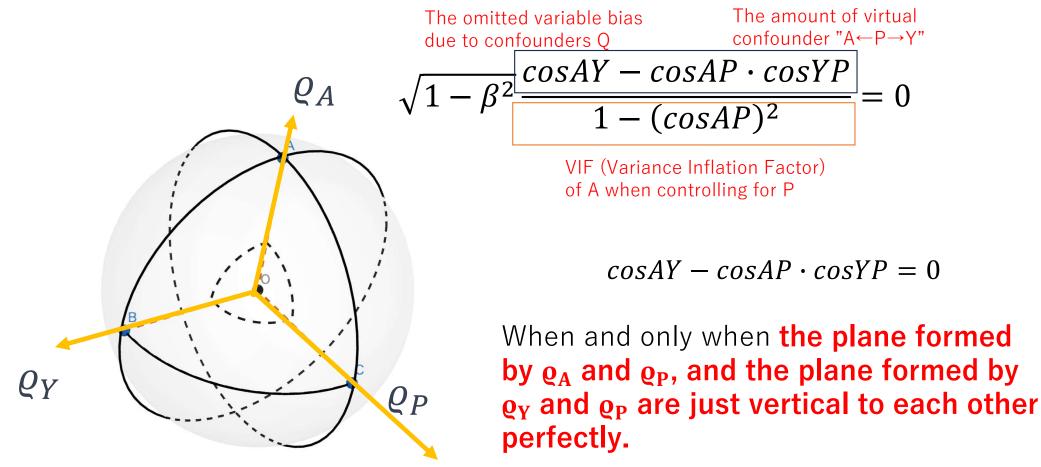
VIF (Variance Inflation Factor) of A when controlling for P

The amount of virtual

The value of p-bias is determined by the relative positional relationship among the three vectors ----  $\varrho_A$ ,  $\varrho_Y$ ,  $\varrho_P$ =How do the generating process of P , A and Y, from Q, are alike to each other.

→ With what positional relationship, p-bias will be exactly zero?

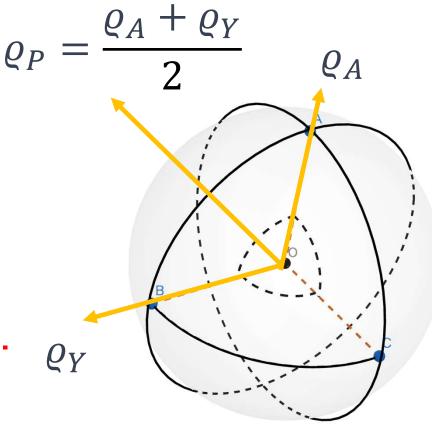
### Hint from Spherical Trigonometry



### An example of a bad proxy

$$p - bias = \frac{cosAY - cosAP \cdot cosYP}{1 - (cosAP)^2}$$
$$= \frac{cos2AP - cosAP \cdot cosAP}{1 - (cosAP)^2} = \frac{-(sinAP)^2}{1 - (cosAP)^2}$$
$$= -1$$
$$< -cosAY$$

In this case, p-bias will be bigger than the omitted variable bias due to confounders Q.



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### Conclusions

- We explored the formula for estimation bias, termed "p-bias," when incorporating a single proxy in a model with multiple unobservable confounders.
- Introducing a proxy influenced by error term of outcomes or instrumental variables will cause a dilemma between partial controlment of unobserved confounders and collider bias. It is necessary to consider case by case whether a proxy is worthy to be controlled for.
- In certain situations, adjusting for such proxy can exaggerate the estimation bias, even without any error term present.
- The value of p-bias is determined by the relative positional relationship among the three vectors  $\varrho_A$ ,  $\varrho_Y$ ,  $\varrho_P$ . These vectors illustrate the similarities in how P, A, and Y are generated from Q.
- From a geometrical perspective, p-bias will be 0 only if the plane formed by  $\varrho_A$  and  $\varrho_P$ , and the plane formed by  $\varrho_Y$  and  $\varrho_P$  are perfectly perpendicular.