

# Non-Smooth Frobenius' Theorem

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# Motivation (1)

I start this talk with an explanation of an inverse problem in economic theory called **integrability problem**. Let  $n \geq 2$ ,  $\Omega = \mathbb{R}_{++}^n \equiv \{x \in \mathbb{R}^n \mid x_i > 0 \text{ for all } i\}$ .  $x_i$  represents the consumption plan of  $i$ -th commodity, and  $p_i > 0$  denotes the corresponding price of  $i$ -th commodity. Therefore, the price system is represented by a positive vector  $p = (p_1, \dots, p_n)$ . For a given price vector  $p$  and income level  $m > 0$ , let  $f(p, m) \in \Omega$  be the consumer's choice of consumption vector. This function  $f$  is called the **demand function**. It is natural that  $p \cdot f(p, m) \leq m$  is assumed, but in consumer theory,  $p \cdot f(p, m) = m$  is usually assumed for some reason. Now, consider a vector field  $g : \Omega \rightarrow \mathbb{R}_{++}^n$  such that

$$f(g(x), g(x) \cdot x) = x$$

for all  $x \in \Omega$ . When the price vector  $p$  is  $g(x)$ , the consumer will purchase  $x$  if he has only enough money to buy just  $x$  under  $p$ . This vector field is called the **inverse demand function**.

## Motivation (2)

If there is a function  $u : \Omega \rightarrow \mathbb{R}$  such that  $f(p, m)$  is the unique maximizer of  $u$  in the set  $\Delta(p, m) = \{x \in \Omega | p \cdot x \leq m\}$ , then we call this  $u$  a **utility function** of the consumer. The utility function is considered as a function that represents the consumer's preference. In economic theory, researchers sometimes want to determine this  $u$ . However, because  $u$  represents the consumer's preference, the information of  $u$  is hidden in their mind. Therefore, it is necessary to estimate  $u(x)$  from only purchase behavior, although it is difficult. Fortunately, both  $f(p, m)$  and  $g(x)$  can directly be estimated from purchase data. Hence, if we can derive  $u(x)$  from  $g(x)$ , then the estimation problem of  $u$  can be changed to the estimation problem of  $g$ , which reduces the difficulty of the problem.

# Motivation (3)

If a quasi-concave function  $u : \Omega \rightarrow \mathbb{R}$  is differentiable and there exists a positive real-valued function  $\lambda(x)$  such that

$$\nabla u(x) = \lambda(x)g(x) \tag{1}$$

for all  $x \in \Omega$ , then by Lagrange's multiplier rule,  $u$  must be a utility function. Therefore, we can obtain  $u$  if we can solve the above **total differential equation** (1). If  $g(x)$  is  $C^1$ , then Frobenius' theorem provides a necessary and sufficient condition for the 'local' existence of the solution  $(u, \lambda)$ .

# Frobenius' Theorem (1)

## Frobenius' Theorem

Suppose that  $n \geq 2$ ,  $U \subset \mathbb{R}^n$  is open and nonempty, and  $g : U \rightarrow \mathbb{R}^n \setminus \{0\}$  is continuously differentiable. Then, for any  $x^* \in U$ , there exists a solution to (1) around  $x^*$  if and only if, the following **Jacobi's integrability condition** holds for all  $x \in U$ : for each  $i, j, k \in \{1, \dots, n\}$  such that  $i \neq j \neq k \neq i$ ,

$$g_i \left( \frac{\partial g_j}{\partial x_k} - \frac{\partial g_k}{\partial x_j} \right) + g_j \left( \frac{\partial g_k}{\partial x_i} - \frac{\partial g_i}{\partial x_k} \right) + g_k \left( \frac{\partial g_i}{\partial x_j} - \frac{\partial g_j}{\partial x_i} \right) = 0. \quad (2)$$

Moreover, for any such solution  $(u, \lambda)$ , any nonempty level set  $u^{-1}(c)$  is an  $n - 1$  dimensional  $C^2$  manifold.

# Frobenius' Theorem (2)

Note: we call not  $u$  but a pair  $(u, \lambda)$  a **solution** to equation (1). Formally, consider the total differential equation (1):

$$\nabla u(x) = \lambda(x)g(x),$$

where  $n \geq 2$ ,  $U \subset \mathbb{R}^n$  is open and nonempty, and  $g : U \rightarrow \mathbb{R}^n \setminus \{0\}$  is given. Then, a pair  $(u, \lambda)$  of real-valued functions defined on  $V \subset U$  is called a **solution** to equation (1) around  $x^*$  if and only if, 1)  $V$  is an open neighborhood of  $x^*$ , 2)  $u$  is continuously differentiable, 3)  $\lambda$  is positive, and 4) the equation (1) holds for all  $x \in V$ . Frobenius' theorem is a result that provides a necessary and sufficient condition for the existence of a local solution to the above total differential equation under the differentiability of  $g$ .

# Frobenius' Theorem (3)

However, in economic environment,  $g$  sometimes becomes not differentiable. Therefore, we want to relax the differentiability assumption of  $g$  from Frobenius' theorem. This is the purpose of this study.

# Rademacher's Theorem

Recall that  $n \geq 2$ ,  $U \subset \mathbb{R}^n$  is open and nonempty, and  $g : U \rightarrow \mathbb{R}^m \setminus \{0\}$  is given. Instead of differentiability, we assume that  $g$  is locally Lipschitz. The following result is the basis of this talk.

## Rademacher's Theorem

Suppose that  $U \subset \mathbb{R}^n$  is open and nonempty, and  $g : U \rightarrow \mathbb{R}^m$  is locally Lipschitz. Then,  $g$  is differentiable almost everywhere.

Using this theorem, we can consider Jacobi's integrability condition a.e. for locally Lipschitz  $g$ .



# Weak Solution to Total Differential Equations

Recall the total differential equation (1):

$$\nabla u(x) = \lambda(x)g(x).$$

We extend the notion of solutions. Let  $x^* \in U$ . We call a pair  $(u, \lambda)$  of real-valued functions defined on  $V \subset U$  a **weak solution** to (1) around  $x^*$  if 1)  $V$  is an open neighborhood of  $x^*$ , 2)  $u$  is locally Lipschitz, 3)  $\lambda$  is positive a.e., 4) any nonempty level set  $u^{-1}(c)$  is an  $n - 1$  dimensional  $C^1$  manifold, and 5) equation (1) holds for almost every  $x \in V$ . Note that, every usual solution  $(u, \lambda)$  is a weak solution. Indeed, because  $u$  is  $C^1$  and  $\nabla u(x) \neq 0$  for all  $x \in V$ , by the preimage theorem,  $u^{-1}(c)$  is either the empty set or a  $n - 1$  dimensional  $C^1$  manifold.

# Main Result

The main result of this talk is as follows.

## Theorem

Suppose that  $n \geq 2$ ,  $U \subset \mathbb{R}^n$  is open and nonempty, and  $g : U \rightarrow \mathbb{R}^n \setminus \{0\}$  is locally Lipschitz. Then,  $g$  satisfies Jacobi's integrability condition (2) for almost every  $x \in U$  if and only if, for every  $x^* \in U$ , there exists a weak solution  $(u, \lambda)$  to (1) around  $x^*$ .

# Idea: Nikliborc's Theorem (1)

Hereafter, I try to explain the idea of the proof. First, Frobenius' theorem is sometimes said to be 'equivalent' to the following theorem.

## Theorem (Nikliborc, 1929)

Let  $n \geq 2$ ,  $U \subset \mathbb{R}^{n+1}$  be open and nonempty, and  $f : U \rightarrow \mathbb{R}^n$  be  $C^1$ . Choose  $(x^*, y^*) \in U$  and consider the following differential equation:

$$\nabla E(x) = f(x, E(x)), \quad E(x^*) = y^*. \quad (3)$$

Define

$$s_{ij}(x, y) = \frac{\partial f_i}{\partial x_j}(x, y) + \frac{\partial f_i}{\partial y}(x, y) f_j(x, y). \quad (4)$$

Then,  $s_{ij} \equiv s_{ji}$  for every  $i, j \in \{1, \dots, n\}$  if and only if for any  $(x^*, y^*) \in U$ , there exists a  $C^2$  solution  $E : V \rightarrow \mathbb{R}$  to (3), where  $V \subset \mathbb{R}^n$  is an open neighborhood of  $x^*$ . Moreover, if  $f$  is  $C^k$ , then  $E$  is  $C^{k+1}$ .

## Idea: Nikliborc's Theorem (2)

If we assume that Frobenius' theorem is correct, we can easily derive Nikliborc's theorem. Actually, define  $g(x, y) = (f(x, y), -1)$ . We can easily check that  $s_{ij} = s_{ji}$  for every  $i, j \in \{1, \dots, n\}$  if and only if  $g$  satisfies Jacobi's integrability condition, and thus, there exists a solution  $(u, \lambda)$  around  $(x^*, y^*)$  such that

$$\nabla u(x, y) = \lambda(x, y)g(x, y).$$

By implicit function theorem, the level set  $u^{-1}(u(x^*, y^*))$  can locally be identified with the graph of a  $C^2$  function  $E$  defined on an open neighborhood of  $x^*$ , and we can easily show that  $E$  is a solution to (3). Therefore, Nikliborc's theorem holds.

# Idea: Nikliborc's Theorem (3)

The converse is also true: that is, if we assume that Nikliborc's theorem is correct, then we can relatively easily derive Frobenius' theorem. To show this, because  $g(x) \neq 0$ , we assume without loss of generality that  $g_n(x) \neq 0$ . Let  $\tilde{x} = (x_1, \dots, x_{n-1})$  when  $x = (x_1, \dots, x_n)$ . Define  $f_i(x) = g_i(x)/g_n(x)$ . Then,  $s_{ij} = s_{ji}$  for  $i, j \in \{1, \dots, n-1\}$  if and only if  $g$  satisfies Jacobi's integrability condition, and thus for each  $x^* \in U$ , there exists a  $C^2$  solution  $E(\tilde{x})$  to the following partial differential equation:

$$\nabla E(\tilde{x}) = f(\tilde{x}, E(\tilde{x})), \quad E(\tilde{x}^*) = x_n^*.$$

Let  $u$  be a continuously differentiable function such that the level set  $u^{-1}(u(x^*))$  coincides with the graph of the solution  $E$  to the above differential equation, and let  $\lambda(x) = \frac{\partial u}{\partial x_n}(x)/g_n(x)$ . Then,  $(u, \lambda)$  is a solution to (1), as desired.

# Idea: Nikliborc's Theorem (4)

Hence, we find that Frobenius' theorem implies Nikliborc's theorem, and vice versa. By the way, recently I obtained an extension of Nikliborc's theorem.

## Theorem (Hosoya, 2021)

Suppose that  $n \geq 2$ ,  $U \subset \mathbb{R}^{n+1}$  is open and nonempty, and  $f : U \rightarrow \mathbb{R}^n$  is locally Lipschitz. Let  $(x^*, y^*) \in U$  and consider the partial differential equation (3). Define  $s_{ij}(x)$  as the equation (4) if it can be defined. Then,  $s_{ij} = s_{ji}$  almost everywhere if and only if for every  $(x^*, y^*) \in U$ , there exists a local  $C^1$  solution  $E : V \rightarrow \mathbb{R}$  to (3), where  $V \subset \mathbb{R}^n$  is an open neighborhood of  $x^*$ .

If we can use this theorem instead of Nikliborc's theorem, then we expect to obtain the corresponding extension of Frobenius' theorem. Actually, our main result is such an extension.

# A Lemma (1)

To derive the main result, we need the following lemma.

## Lemma (Hosoya, 2021)

Suppose that  $n \geq 2$ ,  $U \subset \mathbb{R}^{n+1}$  is open and nonempty,  $f : U \rightarrow \mathbb{R}^n$  is locally Lipschitz, and if we define  $s_{ij}$  as (4),  $s_{ij}(x, y) = s_{ji}(x, y)$  for all  $i, j \in \{1, \dots, n\}$  and almost all  $(x, y) \in U$ . Choose any  $(x^*, y^*) \in U$  and consider the following ordinary differential equation:

$$\dot{c}(t) = f((1-t)x^* + tx, c(t)) \cdot (x - x^*), \quad c(0) = y. \quad (5)$$

Let  $c(t; x, y)$  be the solution function of (5): that is,  $t \mapsto c(t; x, y)$  is a nonextendable solution to (5) with parameter  $(x, y)$ . Let  $V \subset \mathbb{R}^n$  be an open and convex neighborhood of  $x^*$ . Then, there exists a classical solution  $E : V \rightarrow \mathbb{R}$  to (3) if and only if the domain of  $c(t; x, y)$  includes  $[0, 1] \times V \times \{y^*\}$ . Moreover, if such a solution  $E$  exists, then  $E(x) = c(1; x, y^*)$ .

## A Lemma (2)

Recall that the domain of the solution function  $c(t; x, y)$  to (5) is open. Hence, we have obtained the following corollary:

### Corollary

Suppose that  $n \geq 2$ ,  $U \subset \mathbb{R}^{n+1}$  is open and nonempty,  $f : U \rightarrow \mathbb{R}^n$  is locally Lipschitz, and if we define  $s_{ij}$  as (4),  $s_{ij}(x, y) = s_{ji}(x, y)$  for all  $i, j \in \{1, \dots, n\}$  and almost all  $(x, y) \in U$ . Choose any  $(x^*, y^*) \in U$ , and for an open and convex neighborhood  $V \subset \mathbb{R}^n$  of  $x^*$ , suppose that there exists a  $C^1$  solution  $E^{y^*} : V \rightarrow \mathbb{R}$  to (3). Then, there exists  $\varepsilon > 0$  such that if  $|y - y^*| < \varepsilon$ , then the following partial differential equation

$$\nabla E(x) = f(x, E(x)), \quad E(x^*) = y$$

also has a solution  $E^y : V \rightarrow \mathbb{R}$ .



# Sketch of the Proof (1)

Now, suppose that  $g : U \rightarrow \mathbb{R}^n \setminus \{0\}$  is locally Lipschitz and  $x^* \in U$ . Because  $g(x) \neq 0$  for all  $x \in U$ , we assume without loss of generality that  $g_n(x^*) = 0$ . In addition to this, to simplify our arguments, we consider only the case in which  $g_n(x) > 0$  for all  $x \in U$ . Then, we can define  $f_i(x) = g_i(x)/g_n(x)$ . Then,  $g$  satisfies (2) at  $x$  if and only if  $s_{ij}(x) = s_{ji}(x)$ . Hereafter, we write  $\tilde{x} = (x_1, \dots, x_{n-1})$  if  $x = (x_1, \dots, x_n)$ .

Choose any  $x^* \in U$ . If there exists a weak solution  $(u, \lambda)$  to (1) around  $x^*$ , then, for any  $h$  such that  $|h|$  is sufficiently small, there exists a  $C^1$  function  $E^h : V \rightarrow \mathbb{R}$  such that  $u^{-1}(u(\tilde{x}^*, x_n^* + h))$  locally coincides with the graph of  $E^h$ . It is easy to show that  $E^h$  is a  $C^1$  solution to (3), and thus  $s_{ij} = s_{ji}$  a.e.. Hence, if a weak solution exists, then  $g$  must satisfy (2) almost everywhere.

## Sketch of the Proof (2)

Conversely, suppose that  $g$  satisfy (2) almost everywhere. Then,  $s_{ij}(x) = s_{ji}(x)$  for all  $i, j \in \{1, \dots, n-1\}$  and almost all  $x \in U$ . Consider the following differential equation.

$$\nabla E(\tilde{x}) = f(\tilde{x}, E(\tilde{x})), \quad E(\tilde{x}^*) = x_n^* + h. \quad (6)$$

By our Corollary, there exists  $\varepsilon > 0$  such that if  $|h| < 2\varepsilon$ , then for  $V' = \prod_{i=1}^{n-1} ]x_i^* - 2\varepsilon, x_i^* + 2\varepsilon[$ , there exists a  $C^1$  solution  $E^h : V' \rightarrow \mathbb{R}$  to (6).

# Sketch of the Proof (3)

Note that, if  $c(t; \tilde{x}, x_n)$  be the solution function of the following differential equation

$$\dot{c}(t) = f((1-t)\tilde{x}^* + t\tilde{x}, c(t)) \cdot (\tilde{x} - \tilde{x}^*), \quad c(0) = x_n,$$

then, by our Lemma,  $E^h(\tilde{x}) = c(1; \tilde{x}, x_n^* + h)$ . We can easily check that  $c(t; \tilde{x}, x_n)$  is increasing in  $x_n$ , and thus  $E^h(\tilde{x})$  is increasing in  $h$ . Because  $c(t; \tilde{x}, x_n)$  is continuous, if  $\delta > 0$  is sufficiently small, then for all  $\tilde{x} \in V'$  such that  $|\tilde{x}_i - \tilde{x}_i^*| < \delta$  for all  $i \in \{1, \dots, n\}$ ,

$$E^{-\varepsilon}(\tilde{x}) < x_n^* - \delta < x_n^* + \delta < E^{\varepsilon}(\tilde{x}).$$

By the intermediate value theorem, for all  $x_n \in ]x_n^* - \delta, x_n^* + \delta[$ , there uniquely exists  $h^* \in ]-\varepsilon, \varepsilon[$  such that  $E^{h^*}(\tilde{x}) = x_n$ . Define  $V = \prod_{i=1}^n ]x_i^* - \delta, x_i^* + \delta[$ , and  $u(x)$  as such  $h^*$ .

# Sketch of the Proof (4)

By definition, if  $x \in V$  and  $|h| < \varepsilon$ , then

$$h = u(x) \Leftrightarrow c(1; \tilde{x}, x_n^* + h) = x_n. \quad (7)$$

Because  $c(1; \tilde{x}, x_n)$  is increasing in  $x_n$ , we have that  $u(x)$  is increasing in  $x_n$ . Note that, because  $f$  is locally Lipschitz, using Gronwall's inequality, we can show that  $c(t; \tilde{x}, x_n)$  is locally Lipschitz. Therefore, we can assume that there exists  $L > 0$  such that the function

$$w \mapsto f((1-t)\tilde{x}^* + t\tilde{x}, c(t; \tilde{x}, w))$$

has a Lipschitz constant  $L$  on

$[0, 1] \times \prod_{i=1}^{n-1} [x_i^* - \delta, x_i^* + \delta] \times [x_n^* - \varepsilon, x_n^* + \varepsilon]$ . Replacing  $\delta > 0$  so small if needed, we can assume that  $2L\delta < 1$ .

# Sketch of the Proof (5)

Then,

$$\begin{aligned} & c(1; \tilde{x}, w + h) - c(1; \tilde{x}, w) \\ &= h + \int_0^1 [f((1-t)\tilde{x}^* + t\tilde{x}, c(t; \tilde{x}, w + h)) \\ &\quad - f((1-t)\tilde{x}^* + t\tilde{x}, c(t; \tilde{x}, w))] \cdot (\tilde{x} - \tilde{x}^*) dt \\ &\geq h(1 - L\|\tilde{x} - \tilde{x}^*\|) > 2^{-1}h. \end{aligned}$$

Therefore, by equation (7), if  $x_n < x'_n$ , then  $u(\tilde{x}, x'_n) - u(\tilde{x}, x_n) < 2(x'_n - x_n)$ . In other words, the function  $u(x)$  has the Lipschitz constant 2 in  $x_n$ .

# Sketch of the Proof (6)

Choose  $x \in V$  and let  $w = u(x)$ . Recall that  $\nabla E^w(\tilde{x}) = f(x)$ .

Therefore, there exists  $\delta' > 0$  such that if  $|h| < \delta'$ , then

$(x_1, \dots, x_i + h, \dots, x_n) \in V$ , and  $y_n(h) = E^w(x_1, \dots, x_i + h, \dots, x_{n-1}) \in [x_n - (|f_i(x)| + 1)|h|, x_n + (|f_i(x)| + 1)|h|]$ . Define

$y(h) = (x_1, \dots, x_i + h, \dots, x_{n-1}, y_n(h))$ . Then,  $u(y(h)) = u(x) = w$ .

Because  $u$  is Lipschitz in  $x_n$ , there exists  $L' > 0$  independent of  $x, h$  such that

$$\begin{aligned} & |u(x_1, \dots, x_i + h, \dots, x_n) - u(x)| \\ &= |u(x_1, \dots, x_i + h, \dots, x_n) - u(y(h))| \\ &\leq L'(\max_{y \in \tilde{V}} \|f(y)\| + 1)|h|, \end{aligned}$$

which implies that  $u$  is locally Lipschitz on  $V$  in  $x_i$ .

# Sketch of the Proof (7)

Therefore,  $u$  is locally Lipschitz, and by Rademacher's theorem,  $u$  is differentiable almost everywhere. If  $u$  is differentiable at  $x \in V$ , then for  $h = u(x)$ ,  $E_h(\tilde{x}) = x_n$  and the graph of  $E_h$  coincides with  $u^{-1}(h)$ , which implies that  $u^{-1}(h)$  is an  $n - 1$  dimensional  $C^1$  manifold. By the chain rule,

$$\begin{aligned} & \frac{\partial u}{\partial x_i}(x) + \frac{\partial u}{\partial x_n}(x) f_i(x) \\ &= \frac{\partial u}{\partial x_i}(x) + \frac{\partial u}{\partial x_n}(x) \frac{g_i(x)}{g_n(x)} = 0, \end{aligned}$$

which implies that either  $\frac{\partial u}{\partial x_i}(x) = g_i(x) = 0$  or

$$\frac{\frac{\partial u}{\partial x_i}(x)}{g_i(x)} = \frac{\frac{\partial u}{\partial x_n}(x)}{g_n(x)}$$

for every  $i \in \{1, \dots, n - 1\}$ .

# Sketch of the Proof (8)

Hence, if we define

$$\lambda(x) = \frac{\frac{\partial u}{\partial x_n}(x)}{g_n(x)},$$

then

$$\nabla u(x) = \lambda(x)g(x)$$

almost everywhere. We can easily show that  $\lambda(x) > 0$  almost everywhere using equation (7) and local Lipschitz property, and thus this completes the proof of our main theorem.



# Notes on Economic Application (1)

Unfortunately, this weak solution  $u$  is not necessarily quasi-concave, and thus Lagrange's rule may not work well. If  $g$  is  $C^1$ , the quasi-concavity of  $u$  is equivalent to the following condition:

$$v^T g(x) = 0 \Rightarrow v^T \nabla g(x) v \leq 0. \quad (8)$$

This fact is proved in Hosoya (2022, COT). I expect that this result holds even when  $g$  is only locally Lipschitz: that is, I expect that when  $g$  is locally Lipschitz, any weak solution  $u$  is quasi-concave if and only if (8) holds almost everywhere.

## Notes on Economic Application (2)

Another problem is as follows: the above weak solution  $u$  is not entirely defined, but we want to obtain the globally defined utility function  $\tilde{u} : \Omega \rightarrow \mathbb{R}$ . This can be solved by using the following differential equation:

$$\dot{y}(t) = (g(y(t)) \cdot x)v - (g(y(t)) \cdot v)x, \quad y(0) = x.$$

Choose  $x, v \in \Omega$ . Define  $w = ((v \cdot x)v - (v \cdot v)x$ ,  
 $t^*(x, v) = \inf\{t \geq 0 | y(t) \cdot w \geq 0\}$ , and

$$u_v(x) = \frac{\|y(t^*(x, v))\|}{\|v\|}.$$

If  $g$  is  $C^1$ , then using the local solution  $u$ , we can derive that  $u_v$  is a utility function of this consumer. I expect that it is still true even when  $g$  is not differentiable but only locally Lipschitz.

# Extension

Actually, a modern form of Frobenius' theorem is on a theorem for not a single vector field but a finite tuple of linearly independent vector fields  $(g_1, \dots, g_k)$ . This tuple of vector fields is said to **locally integrable** around  $x^*$  if and only if there exists  $u_1, \dots, u_k$  defined on a neighborhood of  $x^*$  such that

$$\nabla u_i(x) = \sum_{j=1}^k \lambda_{ij}(x) g_j(x)$$

for all  $i \in \{1, \dots, k\}$ , and  $(\nabla u_1(x), \dots, \nabla u_k)$  is also linearly independent. I want to extend my result to this problem. However, this is a future task.

Thank you for your attention.